



# 编程语言的设计原理

## Design Principles of Programming Languages

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# Issues in Subtyping



# Typing with Subsumption

*Principle of safe substitution:*

– *a value of one* can *always safely be used* where *a value of the other* is expected

1. a *subtyping relation* between types, written  $S <: T$
2. a rule of *subsumption* stating that, if  $S <: T$ , then any value of type  $S$  can also be regarded as having type  $T$ , i.e.,

$$\frac{\Gamma \vdash t : S \quad S <: T}{\Gamma \vdash t : T} \quad (\text{T-SUB})$$



# Subtype Relation: General rules

A subtyping is *a binary relation* between *types* that is closed under the following rules

$$S <: S \quad (\text{S-REFL})$$

$$\frac{S <: U \quad U <: T}{S <: T} \quad (\text{S-TRANS})$$

$$S <: \text{Top} \quad (\text{S-TOP})$$



# Issues in Subtyping

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For a *given subtyping statement*, there are *multiple rules* that could be used in a derivation.

1. The conclusions of *S-RcdWidth*, *S-RcdDepth*, and *S-RcdPerm* *overlap with each other*.
2. *S-REFL* and *S-TRANS* overlap with *every other rule*.



# Syntax-directed rules

In the simply typed lambda-calculus (without subtyping), *each rule* can be “*read from bottom to top*” in a straightforward way.

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11}}{\Gamma \vdash t_1 t_2 : T_{12}} \quad (\text{T-APP})$$

If we are given some  $\Gamma$  and some  $t$  of the form  $t_1 t_2$ , we can try to *find a type* for  $t$  by

1. finding (recursively) a type for  $t_1$
2. checking that it has the form  $T_{11} \rightarrow T_{12}$
3. finding (recursively) a type for  $t_2$
4. checking that it is the same as  $T_{11}$



# Syntax-directed rules

The reason this works is that we can *divide* the “**positions**” of the typing relation into **input positions** (i.e.,  $\Gamma$  and  $t$ ) and **output positions** ( $T$ ).

- For the input positions, **all metavariables** appearing in the *premises* also appear in the *conclusion* (so we can calculate inputs to the “sub-goals” from the sub-expressions of inputs to the main goal)
- For the output positions, **all metavariables** appearing in the *conclusions* also appear in the *premises* (so we can calculate outputs from the main goal from the outputs of the subgoals)

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11}}{\Gamma \vdash t_1 \ t_2 : T_{12}} \quad (\text{T-APP})$$



# Syntax-directed sets of rules

The *second important point* about the simply typed lambda-calculus is that *the set of typing rules is syntax-directed*:

- For every “**input**”  $\Gamma$  and  $t$ , there is **one rule** that can be used to derive typing statements involving  $t$ , e.g.,
  - if  $t$  is an *application*, then we must proceed by trying to use **T-App**
- If we succeed, then we have found **a type** (indeed, the *unique type*) for  $t$
- If it **fails**, then we know that  $t$  is **not typable**

⇒ no backtracking!





# Non-syntax-directedness of typing

When the system is extended with *subtyping*, **both** aspects of syntax-directedness get broken.

1. The set of typing rules now includes *two* rules that can be used to give a type to terms of a given shape (*the old one* + T-SUB)

$$\frac{\Gamma \vdash t : S \quad S <: T}{\Gamma \vdash t : T} \quad (\text{T-SUB})$$

2. Worse yet, the new rule T-SUB *itself is not syntax directed*: the *inputs* to *the left-hand sub-goal are exactly the same* as the *inputs* to *the main goal*

Hence, if we translate the typing rules naively into a typechecking function, the case corresponding to T-SUB would cause *divergence*



# Non-syntax-directedness of subtyping

Moreover, the *subtyping relation* is *not syntax directed* either

1. There are *lots of ways* to derive a given subtyping statement  
( $\because$  8.2.4 /9.3.3 [uniqueness of types]  $\times$ )
2. The transitivity rule

$$\frac{S <: U \quad U <: T}{S <: T} \quad (\text{S-TRANS})$$

is *badly non-syntax-directed*: the premises contain a *metavariable* (in an “*input position*”) that does *not appear at all in the conclusion*.

To implement this rule naively, we have to *guess* a value for **U**!



# What to do?

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Turn the *declarative version* of subtyping into the *algorithmic version*

The **problem** was that

we don't have an algorithm to decide when  $S <: T$  or  $\Gamma \vdash t : T$

Both sets of rules are not *syntax-directed*



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# Chap 16

# Metatheory of Subtyping

Algorithmic Subtyping

Algorithmic Typing

Joins and Meets



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# Developing an algorithmic subtyping relation



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# Algorithmic Subtyping



# What to do

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How do we change the rules deriving  $S <: T$  to be *syntax-directed*?

There are lots of ways to derive a given subtyping statement  $S <: T$ .

The general idea is to *change this system* so that there is **only one way** to derive it.



# Step 1: simplify record subtyping

**Idea:** combine *all three record subtyping rules* into one “*macro rule*” that captures all of their effects

$$\frac{\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\} \quad k_j = l_i \text{ implies } S_j <: T_i}{\{k_j : S_j^{j \in 1..m}\} <: \{l_i : T_i^{i \in 1..n}\}} \quad (\text{S-RCD})$$

Lemma 16.1.1: If  $\mathbf{S} <: \mathbf{T}$  is derivable from the subtyping rules including **S-RcdDepth**, **S-Rcd-Width**, and **S-Rcd-Perm** (but not **S-Rcd**), then it can also be derived using **S-Rcd** (and not **-RcdDepth**, **S-Rcd-Width**, or **S-Rcd-Perm**), and vice versa.





# Simpler subtype relation

$$S <: S \quad (\text{S-REFL})$$

$$\frac{S <: U \quad U <: T}{S <: T} \quad (\text{S-TRANS})$$

$$\frac{\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\} \quad k_j = l_i \text{ implies } S_j <: T_i}{\{k_j : S_j^{j \in 1..m}\} <: \{l_i : T_i^{i \in 1..n}\}} \quad (\text{S-RCD})$$

$$\frac{T_1 <: S_1 \quad S_2 <: T_2}{S_1 \rightarrow S_2 <: T_1 \rightarrow T_2} \quad (\text{S-ARROW})$$

$$S <: \text{Top} \quad (\text{S-TOP})$$



## Step 2: Get rid of reflexivity

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*Observation:* S-REFL is unnecessary.

*Lemma 16.1.2:*  $S <: S$  can be derived for every type  $S$  without using S-REFL.



# Even simpler subtype relation

$$\frac{S <: U \quad U <: T}{S <: T} \quad (\text{S-TRANS})$$

$$\frac{\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\} \quad k_j = l_i \text{ implies } S_j <: T_i}{\{k_j : S_j^{j \in 1..m}\} <: \{l_i : T_i^{i \in 1..n}\}} \quad (\text{S-RCD})$$

$$\frac{T_1 <: S_1 \quad S_2 <: T_2}{S_1 \rightarrow S_2 <: T_1 \rightarrow T_2} \quad (\text{S-ARROW})$$

$$S <: \text{Top} \quad (\text{S-TOP})$$



## Step 3: Get rid of transitivity

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*Observation:* S-Trans is unnecessary.

*Lemma 16.1.2:* If  $S <: T$  can be derived, then it can be derived without using S-Trans.



# Even simpler subtype relation

$$\frac{\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\} \quad k_j = l_i \text{ implies } S_j <: T_i}{\{k_j : S_j^{j \in 1..m}\} <: \{l_i : T_i^{i \in 1..n}\}} \quad (\text{S-RCD})$$

$$\frac{T_1 <: S_1 \quad S_2 <: T_2}{S_1 \rightarrow S_2 <: T_1 \rightarrow T_2} \quad (\text{S-ARROW})$$

$$S <: \text{Top} \quad (\text{S-TOP})$$



# “Algorithmic” subtype relation

Definition: The *algorithmic subtyping relation* is the least relation on types closed under the following 3 rules

$$\boxed{\vdash} S <: \text{Top} \quad (\text{SA-TOP})$$

$$\frac{\vdash T_1 <: S_1 \quad \vdash S_2 <: T_2}{\vdash S_1 \rightarrow S_2 <: T_1 \rightarrow T_2} \quad (\text{SA-ARROW})$$

$$\frac{\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\} \quad \text{for each } k_j = l_i, \quad \vdash S_j <: T_i}{\vdash \{k_j : S_j^{j \in 1..m}\} <: \{l_i : T_i^{i \in 1..n}\}} \quad (\text{SA-RCD})$$

# Soundness and completeness

Theorem[16.1.5]:  $S <: T$  iff  $\mapsto S <: T$

Terminology:

- The *algorithmic presentation* of subtyping is *sound* with respect to the original, if  $\mapsto S <: T$  implies  $S <: T$   
(*Everything validated by the algorithm is actually true*)
- The *algorithmic presentation* of subtyping is *complete* with respect to the original, if  $S <: T$  implies  $\mapsto S <: T$   
(*Everything true is validated by the algorithm*)



# Subtyping Algorithm

$subtype(S, T) =$

if  $T = \text{Top}$ , then *true*

else if  $S = S_1 \rightarrow S_2$  and  $T = T_1 \rightarrow T_2$

then  $subtype(T_1, S_1) \wedge subtype(S_2, T_2)$

else if  $S = \{k_j: S_j^{j \in 1..m}\}$  and  $T = \{l_i: T_i^{i \in 1..n}\}$

then  $\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\}$

$\wedge$  for all  $i \in 1..n$  there is some  $j \in 1..m$  with  $k_j = l_i$  and  $subtype(S_j, T_i)$

else *false*.





# Decision Procedures

Recall: A decision procedure for a relation  $R \subseteq U$  is a total function  $p$  from  $U$  to  $\{true, false\}$  such that  $p(u) = true$  iff  $u \in R$ .

Is our **subtype** function a decision procedure?

**subtype** is just an implementation of the algorithmic subtyping rules, we have

1. if  $subtype(S, T) = true$ , then  $\mapsto S <: T$

hence, by **soundness** of the algorithmic rules,  $S <: T$

2. if  $subtype(S, T) = false$ , then not  $\mapsto S <: T$

hence, by **completeness** of the algorithmic rules, not  $S <: T$

Q: **What's missing?**



# Decision Procedures

Is our *subtype* function a decision procedure?

Since *subtype* is just **an implementation of the algorithmic subtyping rules**, we have

1. if  $subtype(S, T) = true$ , then  $\mapsto S <: T$   
(hence, by **soundness** of the algorithmic rules,  $S <: T$ )
1. if  $subtype(S, T) = false$ , then not  $\mapsto S <: T$   
(hence, by **completeness** of the algorithmic rules, not  $S <: T$ )

Q: **What's missing?**

A: How do we know that *subtype* is a **total function**?



# Decision Procedures

Is our *subtype* function a decision procedure?

Since *subtype* is just **an implementation of the algorithmic subtyping rules**, we have

1. if  $subtype(S, T) = true$ , then  $\mapsto S <: T$   
(hence, by **soundness** of the algorithmic rules,  $S <: T$ )
1. if  $subtype(S, T) = false$ , then not  $\mapsto S <: T$   
(hence, by **completeness** of the algorithmic rules, not  $S <: T$ )

Q: **What's missing?**

A: How do we know that ***subtype* is a total function?**

**Prove it!**



# Decision Procedures

*Recall:* A decision procedure for a relation  $R \subseteq U$  is *a total function*  $p$  from  $U$  to  $\{true, false\}$  such that  $p(u) = true$  iff  $u \in R$ .

Example:

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$



# Decision Procedures

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Example:

$$U = \{1, 2, 3\}$$

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The function  $p'$  whose graph is

$$\{((1, 2), true), ((2, 3), true)\}$$

*is not* a decision function for  $R$



# Decision Procedures

*Recall:* A decision procedure for a relation  $R \subseteq U$  is *a total function*  $p$  from  $U$  to  $\{true, false\}$  such that  $p(u) = true$  iff  $u \in R$ .

Example:

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The function  $p''$  whose graph is

$$\{((1, 2), true), ((2, 3), true), ((1, 3), false)\}$$

*is also not* a decision function for  $R$



# Decision Procedures

Recall: A decision procedure for a relation  $R \subseteq U$  is *a total function*  $p$  from  $U$  to  $\{true, false\}$  such that  $p(u) = true$  iff  $u \in R$ .

Example:

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The function  $p$  whose graph is

$$\begin{aligned} &\{ ((1, 2), true), ((2, 3), true), \\ &\quad ((1, 1), false), ((1, 3), false), \\ &\quad ((2, 1), false), ((2, 2), false), \\ &\quad ((3, 1), false), ((3, 2), false), ((3, 3), false) \} \end{aligned}$$

is a decision function for  $R$



# Decision Procedures (take 2)

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We want *a decision procedure* to be a *procedure*.

A *decision procedure* for a relation  $R \subseteq U$  is a **computable total function**  $p$  from  $U$  to  $\{true, false\}$  such that

$$p(u) = true \text{ iff } u \in R.$$



# Example

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The function

$$p(x, y) = \begin{array}{l} \text{if } x = 2 \text{ and } y = 3 \text{ then true} \\ \text{else if } x = 1 \text{ and } y = 2 \text{ then true} \\ \text{else false} \end{array}$$

whose graph is

$$\begin{array}{l} \{ ((1, 2), \text{true}), ((2, 3), \text{true}), \\ ((1, 1), \text{false}), ((1, 3), \text{false}), \\ ((2, 1), \text{false}), ((2, 2), \text{false}), \\ ((3, 1), \text{false}), ((3, 2), \text{false}), ((3, 3), \text{false}) \} \end{array}$$

is a decision procedure for  $R$ .

# Example

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The recursively defined *partial function*

$$p(x, y) = \begin{aligned} & \text{if } x = 2 \text{ and } y = 3 \text{ then true} \\ & \text{else if } x = 1 \text{ and } y = 2 \text{ then true} \\ & \text{else if } x = 1 \text{ and } y = 3 \text{ then false} \\ & \text{else } p(x, y) \end{aligned}$$

whose graph is

$$\{((1, 2), \text{true}), ((2, 3), \text{true}), ((1, 3), \text{false})\}$$

is *not* a decision procedure for  $R$ .



# Subtyping Algorithm

The following *recursively defined total function* is a *decision procedure* for the subtype relation:

$subtype(S, T) =$   
if  $T = Top$  then *true*  
else if  $S = S_1 \rightarrow S_2$  and  $T = T_1 \rightarrow T_2$   
    then  $subtype(T_1, S_1) \wedge subtype(S_2, T_2)$   
else if  $S = \{k_j: S_j^{j \in 1..m}\}$  and  $T = \{l_i: T_i^{i \in 1..n}\}$   
    then  $\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\}$   
         $\wedge$  for all  $i \in 1..n$  there is some  $j \in 1..m$  with  $k_j = l_i$  and  $subtype(S_j, T_i)$   
else *false*.



# Subtyping Algorithm

This *recursively defined total function* is a decision procedure for the subtype relation:

$subtype(S, T) =$   
if  $T = \text{Top}$  then *true*  
else if  $S = S_1 \rightarrow S_2$  and  $T = T_1 \rightarrow T_2$   
then  $subtype(T_1, S_1) \wedge subtype(S_2, T_2)$   
else if  $S = \{k_j: S_j^{j \in 1..m}\}$  and  $T = \{l_i: T_i^{i \in 1..n}\}$   
then  $\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\}$   
 $\wedge$  for all  $i \in 1..n$  there is some  $j \in 1..m$  with  $k_j = l_i$  and  $subtype(S_j, T_i)$   
else *false*.

To show this, we *need to prove* :

1. that it returns *true* whenever  $S <: T$ , and
2. that it returns either *true* or *false* on *all inputs*

[16.1.6 Termination Proposition]



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# Algorithmic Typing



# Algorithmic typing

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How do we implement a *type checker* for the lambda-calculus *with subtyping*?

Given a context  $\Gamma$  and a term  $t$ , how do we determine its type  $T$ , such that  $\Gamma \vdash t : T$ ?



# Issue

For the typing relation, we have *just one problematic rule* to deal with: *subsumption rule*

$$\frac{\Gamma \vdash t : S \quad S <: T}{\Gamma \vdash t : T} \quad (\text{T-SUB})$$

Q: where is this rule really needed?

For *applications*, e.g., the term  $(\lambda r: \{x: \text{Nat}\}. r. x)\{x = 0, y = 1\}$  is *not typable* without using subsumption.

Where else??

*Nowhere else!*

Uses of subsumption rule to help typecheck *applications* are the only interesting ones (where subsumption plays a crucial role in typing)



# Plan

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1. Investigate *how subsumption is used* in typing derivations by *looking at examples* of how it can be “*pushed through*” other rules;
2. Use the intuitions gained from these examples to design a new, algorithmic typing relation that
  - *Omits subsumption;*
  - Compensates for its absence by *enriching the application rule;*
3. Show that the *algorithmic typing relation* is essentially *equivalent* to the original, *declarative one*.



# Example (T-ABS)

becomes

$$\begin{array}{c}
 \vdots \qquad \qquad \qquad \vdots \\
 \hline
 \Gamma, x:S_1 \vdash s_2 : S_2 \qquad S_2 <: T_2 \\
 \hline
 \Gamma, x:S_1 \vdash s_2 : T_2 \quad (\text{T-SUB}) \\
 \hline
 \Gamma \vdash \lambda x:S_1 . s_2 : S_1 \rightarrow T_2 \quad (\text{T-ABS}) \\
 \\
 \vdots \qquad \qquad \qquad \vdots \\
 \hline
 \Gamma, x:S_1 \vdash s_2 : S_2 \qquad S_1 <: S_1 \quad (\text{S-REFL}) \qquad S_2 <: T_2 \\
 \hline
 \Gamma \vdash \lambda x:S_1 . s_2 : S_1 \rightarrow S_2 \quad (\text{T-ABS}) \qquad S_1 \rightarrow S_2 <: S_1 \rightarrow T_2 \quad (\text{S-ARROW}) \\
 \hline
 \Gamma \vdash \lambda x:S_1 . s_2 : S_1 \rightarrow T_2 \quad (\text{T-SUB})
 \end{array}$$



# Intuitions

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These examples show that ***we do not need to T-SUB “enable” T-ABS*** :

- given any typing derivation, we **can construct a derivation with the same conclusion** in which ***T-SUB*** is never used immediately before ***T-ABS***.

What about ***T-APP***?

We’ve already observed that ***T-SUB*** is required for typechecking some ***applications***

Therefore we expect to find that we **cannot play the same game** with ***T-APP*** as we’ve done with ***T-ABS***

Let’s see why.

# Example (T-Sub with T-APP on the left)

becomes

$$\begin{array}{c}
 \vdots \\
 \hline
 \Gamma \vdash s_1 : S_{11} \rightarrow S_{12} \\
 \hline
 \Gamma \vdash s_1 : T_{11} \rightarrow T_{12} \quad \text{(T-SUB)} \\
 \hline
 \Gamma \vdash s_1 s_2 : T_{12} \quad \text{(T-APP)} \\
 \hline
 \Gamma \vdash s_1 s_2 : T_{12}
 \end{array}
 \qquad
 \begin{array}{c}
 \vdots \\
 \hline
 T_{11} <: S_{11} \quad S_{12} <: T_{12} \\
 \hline
 S_{11} \rightarrow S_{12} <: T_{11} \rightarrow T_{12} \quad \text{(S-ARROW)} \\
 \hline
 \Gamma \vdash s_2 : T_{11} \\
 \hline
 \Gamma \vdash s_2 : S_{11} \quad \text{(T-SUB)} \\
 \hline
 \Gamma \vdash s_1 s_2 : S_{12} \quad \text{(T-APP)} \\
 \hline
 S_{12} <: T_{12} \\
 \hline
 \Gamma \vdash s_1 s_2 : T_{12} \quad \text{(T-SUB)}
 \end{array}$$

# Example (T-Sub with T-APP on the right)

becomes

$$\frac{\frac{\vdots}{\Gamma \vdash s_1 : T_{11} \rightarrow T_{12}} \quad \frac{\frac{\vdots}{\Gamma \vdash s_2 : T_2} \quad T_2 <: T_{11}}{\Gamma \vdash s_2 : T_{11}} \text{ (T-SUB)}}{\Gamma \vdash s_1 s_2 : T_{12}} \text{ (T-APP)}$$

$$\frac{\frac{\frac{\vdots}{\Gamma \vdash s_1 : T_{11} \rightarrow T_{12}} \quad \frac{\frac{\vdots}{T_2 <: T_{11}} \quad T_{12} <: T_{12}}{T_{11} \rightarrow T_{12} <: T_2 \rightarrow T_{12}} \text{ (S-REFL)}}{\Gamma \vdash s_1 : T_2 \rightarrow T_{12}} \text{ (S-ARROW)} \quad \frac{\vdots}{\Gamma \vdash s_2 : T_2}}{\Gamma \vdash s_1 s_2 : T_{12}} \text{ (T-APP)}$$



# Observations

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We've seen that **uses of subsumption rule** can be “*pushed*” from one of immediately before **T-APP**'s premises to the other, but *cannot be completely eliminated*

# Example (nested uses of T-Sub)

becomes

$$\frac{\frac{\frac{\vdots}{\Gamma \vdash s : S} \quad \frac{\frac{\vdots}{S <: U}}{\Gamma \vdash s : U} \text{ (T-SUB)}}{\Gamma \vdash s : U} \quad \frac{\frac{\vdots}{U <: T}}{\Gamma \vdash s : T} \text{ (T-SUB)}}{\Gamma \vdash s : T} \text{ (T-SUB)}$$

$$\frac{\frac{\frac{\vdots}{\Gamma \vdash s : S} \quad \frac{\frac{\frac{\vdots}{S <: U} \quad \frac{\frac{\vdots}{U <: T}}{S <: T} \text{ (S-TRANS)}}{\Gamma \vdash s : S} \quad \frac{\vdots}{\Gamma \vdash s : T} \text{ (T-SUB)}}{\Gamma \vdash s : T} \text{ (T-SUB)}$$



# Summary

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What we've learned:

- Uses of the **T-Sub** rule can be “*pushed down*” through typing derivations until they encounter **either**
  1. a use of **T-App**, **or**
  2. the *root* of the derivation tree.
- In both cases, *multiple uses of T-Sub can be coalesced into a single one.*

This suggests a notion of “*normal form*” for typing derivations, in which there is

- **exactly one use** of **T-Sub** before each use of **T-App**,
- **one use** of **T-Sub** at **the very end** of the derivation,
- no uses of **T-Sub** anywhere else.



# Algorithmic Typing

The next step is to “**build in**” the use of subsumption rule in *application rules*, by *changing* the **T-App** rule to *incorporate a subtyping premise*

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_2 \quad \boxed{\vdash T_2 <: T_{11}}}{\Gamma \vdash t_1 t_2 : T_{12}}$$

Given any typing derivation, we can now

1. **normalize** it, to *move all uses of subsumption rule* to either just *before applications* (in the right-hand premise) or *at the very end*
2. **replace** uses of **T-App** with **T-SUB** in the right-hand premise by uses of the extended rule above

This yields a derivation in which there is **just one use of subsumption**, at the very end!





# Minimal Types

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But... if subsumption is only used at the very end of derivations, then it is actually *not needed* in order to show that *any term is typable*!

It is just used to give *more* types to terms that have already been shown to have a type.

In other words, if we *dropped subsumption completely* (after refining the application rule), we would still be able to give types to exactly the same set of terms — we just would not be able to give as *many types* to some of them.

If we drop subsumption, then the remaining rules will assign a *unique, minimal* type to *each typable term*

For purposes of building a typechecking algorithm, this is enough



# Final Algorithmic Typing Rules

$$\frac{x:T \in \Gamma}{\Gamma \vdash x : T} \quad (\text{TA-VAR})$$

$$\frac{\Gamma, x:T_1 \vdash t_2 : T_2}{\Gamma \vdash \lambda x:T_1. t_2 : T_1 \rightarrow T_2} \quad (\text{TA-ABS})$$

$$\frac{\Gamma \vdash t_1 : T_1 \quad T_1 = T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_2 \quad \boxed{\vdash T_2 <: T_{11}}}{\Gamma \vdash t_1 t_2 : T_{12}} \quad (\text{TA-APP})$$

$$\frac{\text{for each } i \quad \Gamma \vdash t_i : T_i}{\Gamma \vdash \{l_1=t_1 \dots l_n=t_n\} : \{l_1:T_1 \dots l_n:T_n\}} \quad (\text{TA-RCD})$$

$$\frac{\Gamma \vdash t_1 : R_1 \quad R_1 = \{l_1:T_1 \dots l_n:T_n\}}{\Gamma \vdash t_1.l_i : T_i} \quad (\text{TA-PROJ})$$



# Completeness of the algorithmic rules

## Theorem [Minimal Typing]:

If  $\Gamma \vdash t : T$ , then  $\Gamma \mapsto t : S$  for some  $S <: T$ .

Proof: Induction on *typing derivation*.

N.b.: All the messing around with transforming derivations was just to build intuitions and *decide what algorithmic rules* to write down and *what property to prove*:

the proof itself is *a straightforward induction on typing derivations*.



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# Meets and Joins



# Adding Booleans

Suppose we want to add *booleans* and *conditionals* to the language we have been discussing.

For the declarative presentation of the system, we just add in the appropriate *syntactic forms*, *evaluation rules*, and *typing rules*.

$$\begin{array}{l} \Gamma \vdash \text{true} : \text{Bool} \qquad \qquad \qquad (\text{T-TRUE}) \\ \Gamma \vdash \text{false} : \text{Bool} \qquad \qquad \qquad (\text{T-FALSE}) \\ \hline \frac{\Gamma \vdash t_1 : \text{Bool} \quad \Gamma \vdash t_2 : T \quad \Gamma \vdash t_3 : T}{\Gamma \vdash \text{if } t_1 \text{ then } t_2 \text{ else } t_3 : T} \qquad (\text{T-IF}) \end{array}$$



# A Problem with Conditional Expressions

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For the *algorithmic presentation* of the system, however, we encounter a little difficulty.

What is the minimal type of

*if true then {x = true, y = false} else {x = true, z = true} ?*

# The Algorithmic Conditional Rule

More generally, we can use subsumption to give an expression

$\text{if } t_1 \text{ then } t_2 \text{ else } t_3$

any type that is a possible type of both  $t_2$  and  $t_3$ .

So the *minimal type* of the *conditional* is the

*least common supertype* (or *join*) of

the minimal type of  $t_2$  and the minimal type of  $t_3$

$$\frac{\Gamma \vdash t_1 : \text{Bool} \quad \Gamma \vdash t_2 : T_2 \quad \Gamma \vdash t_3 : T_3}{\Gamma \vdash \text{if } t_1 \text{ then } t_2 \text{ else } t_3 : T_2 \vee T_3} \quad (\text{T-IF})$$

Q: Does such a type exist for every  $T_2$  and  $T_3$  ??



# Existence of Joins

**Theorem:** For every pair of types  $S$  and  $T$ , there is a type  $J$  such that

1.  $S <: J$
2.  $T <: J$
3. If  $K$  is a type such that  $S <: K$  and  $T <: K$ , then  $J <: K$ .

i.e.,  $J$  is the *smallest type* that is a supertype of both  $S$  and  $T$ .

How to prove it?



# Calculating Joins



$$S \vee T = \begin{cases} \text{Bool} & \text{if } S = T = \text{Bool} \\ M_1 \rightarrow J_2 & \text{if } S = S_1 \rightarrow S_2 \quad T = T_1 \rightarrow T_2 \\ & S_1 \wedge T_1 = M_1 \quad S_2 \vee T_2 = J_2 \\ \{j_l : J_l \mid l \in 1..q\} & \text{if } S = \{k_j : S_j \mid j \in 1..m\} \\ & T = \{l_i : T_i \mid i \in 1..n\} \\ & \{j_l \mid l \in 1..q\} = \{k_j \mid j \in 1..m\} \cap \{l_i \mid i \in 1..n\} \\ & S_j \vee T_i = J_l \quad \text{for each } j_l = k_j = l_i \\ \text{Top} & \text{otherwise} \end{cases}$$

# Examples

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What are the joins of the following pairs of types?

1.  $\{x: \text{Bool}, y: \text{Bool}\}$  and  $\{y: \text{Bool}, z: \text{Bool}\}$ ?
2.  $\{x: \text{Bool}\}$  and  $\{y: \text{Bool}\}$ ?
3.  $\{x: \{a: \text{Bool}, b: \text{Bool}\}\}$  and  $\{x: \{b: \text{Bool}, c: \text{Bool}\}, y: \text{Bool}\}$ ?
4.  $\{\}$  and  $\text{Bool}$ ?
5.  $\{x: \{\}\}$  and  $\{x: \text{Bool}\}$ ?
6.  $\text{Top} \rightarrow \{x: \text{Bool}\}$  and  $\text{Top} \rightarrow \{y: \text{Bool}\}$ ?
7.  $\{x: \text{Bool}\} \rightarrow \text{Top}$  and  $\{y: \text{Bool}\} \rightarrow \text{Top}$ ?



# Meets

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To calculate joins of arrow types, we also need to be able to calculate **meets** (greatest lower bounds)!

Unlike joins, meets *do not necessarily exist*.

E.g., `Bool → Bool` and `{ }` have *no common subtypes*, so they certainly don't have a greatest one!

# Existence of Meets

**Theorem:** For every pair of types  $S$  and  $T$ , we say that a type  $M$  is a meet of  $S$  and  $T$ , written  $S \wedge T = M$  if

1.  $M <: S$
2.  $M <: T$
3. If  $O$  is a type such that  $O <: S$  and  $O <: T$ , then  $O <: M$ .

i.e.,  $M$  (when it exists) is the *largest type* that is a subtype of both  $S$  and  $T$ .

Jargon: In the simply typed lambda calculus with subtyping, records, and booleans ...

- The subtype relation *has joins*
- The subtype relation *has bounded meets*

# Calculating Meets

$S \wedge T =$

{	$S$	if $T = \text{Top}$
	$T$	if $S = \text{Top}$
	$\text{Bool}$	if $S = T = \text{Bool}$
	$J_1 \rightarrow M_2$	if $S = S_1 \rightarrow S_2$ $T = T_1 \rightarrow T_2$ $S_1 \vee T_1 = J_1$ $S_2 \wedge T_2 = M_2$
	$\{m_l : M_l \mid l \in 1..q\}$	if $S = \{k_j : S_j \mid j \in 1..m\}$ $T = \{l_i : T_i \mid i \in 1..n\}$ $\{m_l \mid l \in 1..q\} = \{k_j \mid j \in 1..m\} \cup \{l_i \mid i \in 1..n\}$ $S_j \wedge T_i = M_l$ for each $m_l = k_j = l_i$ $M_l = S_j$ if $m_l = k_j$ occurs only in $S$ $M_l = T_i$ if $m_l = l_i$ occurs only in $T$
	$\text{fail}$	otherwise

# Examples

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What are the meets of the following pairs of types?

1.  $\{x: \text{Bool}, y: \text{Bool}\}$  and  $\{y: \text{Bool}, z: \text{Bool}\}$ ?
2.  $\{x: \text{Bool}\}$  and  $\{y: \text{Bool}\}$ ?
3.  $\{x: \{a: \text{Bool}, b: \text{Bool}\}\}$  and  $\{x: \{b: \text{Bool}, c: \text{Bool}\}, y: \text{Bool}\}$ ?
4.  $\{\}$  and  $\text{Bool}$ ?
5.  $\{x: \{\}\}$  and  $\{x: \text{Bool}\}$ ?
6.  $\text{Top} \rightarrow \{x: \text{Bool}\}$  and  $\text{Top} \rightarrow \{y: \text{Bool}\}$ ?
7.  $\{x: \text{Bool}\} \rightarrow \text{Top}$  and  $\{y: \text{Bool}\} \rightarrow \text{Top}$ ?



# Homework😊

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- Read and digest chapter 16 & 17
- HW:
  - 16.1.2; 16.2.6; 16.4.1