

Design Principles of Programming Languages 编程语言的设计原理

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Type Inference 类型推导

Type Erasure & Inference for System F



```
\begin{aligned} \textit{erase}(x) &\stackrel{\text{def}}{=} x \\ \textit{erase}(\lambda x : T_1 \cdot t_2) &\stackrel{\text{def}}{=} \lambda x . \, \textit{erase}(t_2) \\ \textit{erase}(t_1 \ t_2) &\stackrel{\text{def}}{=} \textit{erase}(t_1) \, \textit{erase}(t_2) \\ \textit{erase}(\lambda X . \ t_2) &\stackrel{\text{def}}{=} \textit{erase}(t_2) \\ \textit{erase}(t_1 \ [T_2]) &\stackrel{\text{def}}{=} \textit{erase}(t_1) \end{aligned}
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Definition (Type Inference)

Given an untyped term \mathfrak{m} , whether we can find some well-typed term \mathfrak{t} such that $\mathit{erase}(\mathfrak{t})=\mathfrak{m}$.

Theorem (Wells, 1994¹)

Type inference for System F is **undecidable**.

B. Wells. 1994. Typability and Type Checking in the Second-Order λ-Calculus Are Equivalent and Undecidable. In Logic in Computer Science (LICS'94), 176-185. DOI: 10.1109/LICS.1994.316068.
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Partial Erasure & Inference for System F



$$\begin{aligned} \textit{erase}_p(x) &\stackrel{\text{def}}{=} x \\ \textit{erase}_p(\lambda x : T_1 . \ t_2) &\stackrel{\text{def}}{=} \lambda x : T_1 . \ \textit{erase}_p(t_2) \\ \textit{erase}_p(t_1 \ t_2) &\stackrel{\text{def}}{=} \textit{erase}_p(t_1) \ \textit{erase}_p(t_2) \\ \textit{erase}_p(\lambda X . \ t_2) &\stackrel{\text{def}}{=} \lambda X . \ \textit{erase}_p(t_2) \\ \textit{erase}_p(t_1 \ [T_2]) &\stackrel{\text{def}}{=} \textit{erase}_p(t_1) \ [] \end{aligned}$$

Theorem (Boehm 1985², 1989³)

It is **undecidable** whether, given a closed term s in which type applications are marked but the arguments are omitted, there is some well-typed System-F term t such that $erase_p(t) = s$.

²H.-J. Boehm, 1985, Partial Polymorphic Type Inference is Undecidable. In Symp. on Foundations of Computer Science (SFCS'85), 339-345, DOI: 10.1109/SFCS.1985.44.

³ H.-J. Boehm. 1989. Type Inference in the Presence of Type Abstraction. In Prog. Lang. Design and Impl. (PLDI'89), 192-206. DOI: 10.1145/73141.74835.

Fragments of System F



Prenex Polymorphism

- Type variables range only over quantifier-free types (monotypes).
- Quantified types (**polytypes**) are not allows to appear on the left-hand sides of arrows.

Rank-2 Polymorphism

A type is said to be of rank 2 if no path from its root to a \forall quantifier passes to the left of 2 or more arrows.

$$\begin{array}{c} (\forall X.X \to X) \to \mathsf{Nat} & \checkmark \\ \mathsf{Nat} \to ((\forall X.X \to X) \to (\mathsf{Nat} \to \mathsf{Nat})) & \checkmark \\ ((\forall X.X \to X) \to \mathsf{Nat}) \to \mathsf{Nat} & \checkmark \\ \end{array}$$

Remark

Prenex polymorphism is a $\boldsymbol{predicative}$ and rank-1 fragment of System F.

Type inference for ranks 2 and lower is **decidable**!

Simply-Typed Lambda-Calculus with Type Variables



Syntax

$$\begin{split} t &\coloneqq x \mid \lambda x : T. \ t \mid t \ t \mid \dots \\ \nu &\coloneqq \lambda x : T. \ t \mid \dots \\ T &\coloneqq X \mid T \to T \mid \dots \\ \Gamma &\coloneqq \varnothing \mid \Gamma, x : T \end{split}$$

Typing

$$\frac{x:1\in I}{\Gamma\vdash x\cdot T}$$
 T-Var

$$\frac{x: T \in \Gamma}{\Gamma \vdash x: T} \text{ T-Var} \qquad \frac{\Gamma, x: T_1 \vdash t_2: T_2}{\Gamma \vdash \lambda x: T_1. t_2: T_1 \rightarrow T_2} \text{ T-Abs}$$

$$\frac{\Gamma \vdash t_1: T_{11} \rightarrow T_{12} \qquad \Gamma \vdash t_2: T_{11}}{\Gamma \vdash t_1\: t_2: T_{12}} \; \text{T-App}$$

Type Substitutions



Definition

A type substitution is a finite mapping from type variables to types.

Example

We define $\sigma \stackrel{\text{def}}{=} [X \mapsto \text{Bool}, Y \mapsto U]$ for the substitution that maps X to Bool and Y to U.

We write $dom(\cdot)$ for left-hand sides of pairs in a substitution, e.g., $dom(\sigma) = \{X, Y\}$.

We write $range(\cdot)$ for the right-hand sides of pairs in a substitution, e.g., $range(\sigma) = \{Bool, U\}$.

Remark

The pairs of a substitution are applied **simultaneously**.

For example, $[X \mapsto \mathsf{Bool}, Y \mapsto X \to X]$ maps Y to $X \to X$, not $\mathsf{Bool} \to \mathsf{Bool}$.

Type Substitutions



Application of a Substitution to Types

$$\begin{split} \sigma(X) &\stackrel{\text{def}}{=} \begin{cases} \mathsf{T} & \text{if } (X \mapsto \mathsf{T}) \in \sigma \\ X & \text{if } X \text{ is not in the domain of } \sigma \end{cases} \\ \sigma(\mathsf{Nat}) &\stackrel{\text{def}}{=} \mathsf{Nat} \\ \sigma(\mathsf{Bool}) &\stackrel{\text{def}}{=} \mathsf{Bool} \\ \sigma(\mathsf{T}_1 \to \mathsf{T}_2) &\stackrel{\text{def}}{=} \sigma(\mathsf{T}_1) \to \sigma(\mathsf{T}_2) \end{split}$$

Composition of Substitutions

$$\sigma \circ \gamma \stackrel{\text{def}}{=} \left[\begin{array}{ll} X \mapsto \sigma(T) & \text{for each } (X \mapsto T) \in \gamma \\ X \mapsto T & \text{for each } (X \mapsto T) \in \sigma \text{ with } X \not \in \textit{dom}(\gamma) \end{array} \right]$$

Type Substitutions



Application of a Substitution to Contexts

$$\sigma(x_1:T_1,\ldots,x_n:T_n)\stackrel{\text{def}}{=}(x_1:\sigma(T_1),\ldots,x_n:\sigma(T_n))$$

Application of a Substitution to Terms

$$\sigma(x) \stackrel{\text{def}}{=} x$$

$$\sigma(\lambda x : T_1. t_2) \stackrel{\text{def}}{=} \lambda x : \sigma(T_1). \sigma(t_2)$$

$$\sigma(t_1 t_2) \stackrel{\text{def}}{=} \sigma(t_1) \sigma(t_2)$$

Theorem (Preservation of Typing under a Substitution)

If σ is any type substitution and $\Gamma \vdash t : T$, then $\sigma(\Gamma) \vdash \sigma(t) : \sigma(T)$.

Type Inference



Definition (Type Inference in terms of Substitutions)

Let Γ be a context and t be a term. **A solution for** (Γ, t) is a pair (σ, T) such that $\sigma(\Gamma) \vdash \sigma(t) : T$.

Remark (Two Views of $\sigma(\Gamma) \vdash \sigma(t) : T$)

- **Type Infernece**: does there exist some σ such that $\sigma(\Gamma) \vdash \sigma(t)$: T for some T?
- Another view: for **every** σ , do we have $\sigma(\Gamma) \vdash \sigma(t)$: T for some T?
 - This corresponds to **parametric polymorphism**, e.g., $\varnothing \vdash \lambda f: X \to X$. $\lambda a: X$. $f(fa): (X \to X) \to X \to X$.

Example

Let $\Gamma \stackrel{\text{def}}{=} f: X$, $\alpha: Y$ and $t \stackrel{\text{def}}{=} f$ α . Below gives some solutions for (Γ, t) :

σ	Ť	σ	T
$[X \mapsto Y \to Nat]$	Nat	$[X \mapsto Y \to Z]$	Z
$[X \mapsto Y o Z, Z \mapsto Nat]$	Z	$[X \mapsto Y o Nat o Nat]$	Nat o Nat
$[X\mapstoNat\toNat,Y\mapstoNat]$	Nat		

Erasure (revisited)



$$\begin{aligned} \textit{erase}(x) &\stackrel{\text{def}}{=} x \\ \textit{erase}(\lambda x : T_1 \cdot t_2) &\stackrel{\text{def}}{=} \lambda x \cdot \textit{erase}(t_2) \\ \textit{erase}(t_1 \ t_2) &\stackrel{\text{def}}{=} \textit{erase}(t_1) \textit{erase}(t_2) \end{aligned}$$

Definition (Type Inference)

Let Γ be a context and \mathfrak{m} be an untyped term. A solution for (Γ, \mathfrak{m}) is a substitution (σ, Γ) such that $\sigma(\Gamma) \vdash \mathfrak{m} : \Gamma$.

$$\frac{x:T\in\Gamma}{\Gamma\vdash x:T} \text{ T-Var}$$

$$\frac{\Gamma, x : T_1 \vdash t_2 : T_2}{\Gamma \vdash \lambda x. t_2 : T_1 \rightarrow T_2} \text{ T-Abs}$$

$$\frac{x:T\in\Gamma}{\Gamma\vdash x:T} \text{ T-Var} \qquad \qquad \frac{\Gamma,x:\textcolor{red}{T_1}\vdash t_2:\textcolor{blue}{T_2}}{\Gamma\vdash \lambda x.\ t_2:\textcolor{blue}{T_1}\to \textcolor{blue}{T_2}} \text{ T-Abs} \qquad \qquad \frac{\Gamma\vdash t_1:\textcolor{blue}{T_{11}}\to\textcolor{blue}{T_{12}}}{\Gamma\vdash t_1\ t_2:\textcolor{blue}{T_{12}}} \text{ T-App}$$

Given the derivation, it is trivial to construct a well-typed term t such that erase(t) = m.

Constraint Typing



Definition

A constraint set C is a set of equations $\{S_i = T_i^{1} \cdots^n \}$ where S_i 's and T_i 's are types.

$\Gamma \vdash t : T \mid_{\mathcal{X}} C$: "term t has type T under context Γ whenever constraints C are satisfied"

The set X is used to track **new** type variables introduced in each subderivation.

$$\frac{x:\mathsf{T}\in\Gamma}{\Gamma\vdash x:\mathsf{T}\mid_\varnothing\{\}}\;\mathsf{CT\text{-}Var}\qquad \frac{\Gamma,x:\mathsf{T}_1\vdash \mathsf{t}_2:\mathsf{T}_2\mid_\mathfrak{X}C}{\Gamma\vdash \lambda x:\mathsf{T}_1:\mathsf{t}_2:\mathsf{T}_1\to \mathsf{T}_2\mid_\mathfrak{X}C}\;\mathsf{CT\text{-}Abs}$$

$$\frac{\Gamma\vdash \mathsf{t}_1:\mathsf{T}_1\mid_{\mathscr{X}_1}C_1}{\mathsf{X}\not\in\mathscr{X}_1,\mathscr{X}_2,\mathsf{T}_1,\mathsf{T}_2,C_1,C_2,\Gamma,\mathsf{t}_1,\mathsf{t}_2}\qquad \mathscr{X}_1\cap\mathscr{X}_2=\mathscr{X}_1\cap FV(\mathsf{T}_2)=\mathscr{X}_2\cap FV(\mathsf{T}_1)=\varnothing}{\mathsf{X}\not\in\mathscr{X}_1,\mathscr{X}_2,\mathsf{T}_1,\mathsf{T}_2,C_1,C_2,\Gamma,\mathsf{t}_1,\mathsf{t}_2}\qquad C'=C_1\cup C_2\cup\{\mathsf{T}_1=\mathsf{T}_2\to\mathsf{X}\}}$$

$$\frac{\mathsf{CT\text{-}Ap}}{\Gamma\vdash \mathsf{t}_1\;\mathsf{t}_2:\mathsf{X}\mid_{\mathscr{X}_1\cup\mathscr{X}_2\cup\{\mathsf{X}\}}C'}\;\mathsf{CT\text{-}Ap}$$

Question (Exercise 22.3.3)

Construct a constraint typing derivation for $\lambda x: X$. $\lambda y: Y$. $\lambda z: Z$. (x z) (y z).

Solutions for Constraint Typing



Definition

A substitution σ is said to **unify** an equation S = T if $\sigma(S) = \sigma(T)$.

We say that σ unifies a constraint set C if it unifies every equation in C.

Definition

Suppose that $\Gamma \vdash t : S \mid_{\mathcal{X}} C$. A solution for (Γ, t, S, C) is a pair (σ, T) such that σ unified C and $\sigma(S) = T$.

Remark

Recall that **a solution for** (Γ, t) is a pair (σ, T) such that $\sigma(\Gamma) \vdash \sigma(t) : T$.

What are the relation between the two definitions of solutions for type inference?

Properties of Constraint Typing



Theorem (Soundness)

Suppose that $\Gamma \vdash t : S \mid C$. If (σ, T) is a solution for (Γ, t, S, C) , then it is also a solution for (Γ, t) .

Proof Sketch

By induction on the derivation of constraint typing.

Theorem (Completeness)

Suppose $\Gamma \vdash t : S \mid_{\mathcal{X}} C$. If (σ, T) is a solution for (Γ, t) and $dom(\sigma) \cap \mathcal{X} = \emptyset$, then there is some solution (σ', T) for (Γ, t, S, C) such that $\sigma' \setminus \mathcal{X} = \sigma$.

Proof Sketch

By induction on the derivation of constraint typing.

Unification



Remark

Hindley (1969)⁴ and Milner (1978)⁵ apply unification to calculate **a "best" solution** to a given constraint set.

Definition

A substitution σ is less specific (or **more general**) than a substitution σ' , written $\sigma \sqsubseteq \sigma'$, if $\sigma' = \gamma \circ \sigma$ for some γ .

A **principal unifier** (or sometimes **most general unifier**) for a constraint set C is a substitution σ that unifies C and such that $\sigma \sqsubseteq \sigma'$ for every substitution σ' unifying C.

Question (Exercise 22.4.3)

Write down principal unifiers (when they exist) for the following sets of constraints:

$$\begin{aligned} \{X = \mathsf{Nat}, Y = X \to X\} & \{\mathsf{Nat} \to \mathsf{Nat} = X \to Y\} & \{X \to Y = Y \to \mathsf{Z}, \mathsf{Z} = \mathsf{U} \to \mathsf{W}\} \\ \{\mathsf{Nat} = \mathsf{Nat} \to Y\} & \{Y = \mathsf{Nat} \to Y\} & \{\} \end{aligned}$$

⁴R. Hindley. 1969. The Principal Type-Scheme of an Object in Combinatory Logic. Trans. of the American Math. Society, 146, 29–60. doi: 10.2307/1995158.

⁵R. Milner. 1978. A Theory of Type Polymorphism in Programming. *J. Comput. Syst. Sci.*, 17, 348–375, 3. doi: 10.1016/0022-0000(78)90014-4.

Unification Algorithm



```
unify(C) = if C = \emptyset. then []
                    else let \{S = T\} \cup C' = C in
                       if S = T
                          then unify(C')
                       else if S = X and X \notin FV(T)
                          then unify([X \mapsto T]C') \circ [X \mapsto T]
                       else if T = X and X \notin FV(S)
                          then unify([X \mapsto S]C') \circ [X \mapsto S]
                       else if S = S_1 \rightarrow S_2 and T = T_1 \rightarrow T_2
                          then unify(C' \cup \{S_1 = T_1, S_2 = T_2\})
                       else
                          fail
```

What if we omit the occur checks (i.e., $X \notin FV(T)$ and $X \notin FV(S)$)?

Correctness of Unification Algorithm



Theorem

The algorithm *unify* always terminates, failing when given a non-unifiable constraint set as input and otherwise returning a principal unifier.

Proof Sketch

- **Termination**: define the $\frac{degree}{degree}$ of C to be the pair (number of distinct type variables, total size of types).
- unify(C) returns a unifier: prove by induction on the number of recursive calls to unify.
 - Fact: if σ unifies $[X \mapsto T]D$, then $\sigma \circ [X \mapsto T]$ unifies $\{X = T\} \cup D$.
- unify(C) returns a **principal** unifier: prove by induction on the number of recursive calls.

Principal Types



Definition

A principal solution for (Γ, t, S, C) is a solution (σ, T) such that, $\sigma \sqsubseteq \sigma'$ for any other solution (σ', T') . When (σ, T) is a principal solution, we call T **a principal type** of t under Γ .

Theorem

If (Γ, t, S, C) has any solution, then it has a principal one.

The unify algorithm can be used to determine if there exists a solution and, if so, to calculate a principal one.

Corollary

It is decidable whether (Γ, t) has a solution.

Remark

Recall that type inference for System F is **undecidable**.

Recall: Prenex Polymorphism



Prenex Polymorphism

- Type variables range only over quantifier-free types (monotypes).
- Quantified types (**polytypes**) are not allows to appear on the left-hand sides of arrows.

Let-Polymorphism is a Variant of Prenex Polymorphism where ...

- Quantifiers can only occur at the outermost level of types.
- Type abstractions are implicitly introduced at let-bindings.
- Type applications are implicitly introduced at **variables**.

Let-Polymorphism as a Fragment of System F



Syntax

```
\begin{split} t &\coloneqq x \mid \lambda x : T \cdot t \mid t \, t \mid \textbf{let} \, x = \textbf{tint} \mid \dots \\ \nu &\coloneqq \lambda x : T \cdot t \mid \dots \\ T &\coloneqq X \mid T \to T \mid \dots \\ T &\coloneqq \forall X_1 \dots X_n \cdot T \\ \Gamma &\coloneqq \varnothing \mid \Gamma, x : T \end{split}
```

Typing

$$\begin{split} \frac{\Gamma \vdash \mathsf{t}_1 : \mathsf{T}_1 & \quad \{\mathsf{X}_1, \dots, \mathsf{X}_n\} = \mathit{FV}(\mathsf{T}_1) \setminus \mathit{FV}(\Gamma) & \quad \mathbb{T}_1 = \forall \mathsf{X}_1 \dots \mathsf{X}_n. \, \mathsf{T}_1 & \quad \Gamma, \mathsf{x} : \mathbb{T}_1 \vdash \mathsf{t}_2 : \mathsf{T}_2 \\ & \quad \Gamma \vdash \mathsf{let} \, \mathsf{x} = \mathsf{t}_1 \, \, \mathsf{in} \, \mathsf{t}_2 : \mathsf{T}_2 \\ & \quad \frac{\mathsf{x} : \forall \mathsf{X}_1 \dots \mathsf{X}_n. \, \mathsf{T} \in \Gamma}{\Gamma \vdash \mathsf{x} : [\mathsf{X}_1 \mapsto \mathsf{S}_1, \dots, \mathsf{X}_n \mapsto \mathsf{S}_n] \mathsf{T}} \, \, \mathsf{T\text{-Var}} \end{split}$$

Let-Polymorphism as a Fragment of System F



Example

Observation

Let-polymorphism can be equivalently implemented in simply-typed lambda-calculus with the following rule:

$$\frac{\Gamma \vdash t_1 : T_1 \qquad \Gamma \vdash [x \mapsto t_1]t_2 : T_2}{\Gamma \vdash \mathsf{let}\, x = t_1 \; \mathsf{in}\, t_2 : T_2} \; \mathsf{T\text{-}LetPoly}$$

Constraint Typing for Let-Polymorphism



$$\begin{split} & \Gamma \vdash t_1 : T_1 \mid_{\mathcal{X}_1} C_1 \quad \{X_1, \dots, X_n\} = FV(T_1) \cup FV(C_1) \setminus FV(\Gamma) \\ & \frac{\mathbb{T}_1 = \forall X_1 \dots X_n. C_1 \supset T_1 \quad \Gamma, x : \mathbb{T}_1 \vdash t_2 : T_2 \mid_{\mathcal{X}_2} C_2}{\Gamma \vdash \text{let } x = t_1 \text{ in } t_2 : T_2 \mid_{\mathcal{X}_1 \cup \mathcal{X}_2} C_1 \cup C_2} \text{ CT-Let} \\ & \frac{x : \forall X_1 \dots X_n. C \supset T \in \Gamma \quad Y_1, \dots, Y_n \not \in X_1, \dots, X_n, T, \Gamma}{\Gamma \vdash x : [X_1 \mapsto Y_1, \dots, X_n \mapsto Y_n]T \mid_{\{Y_1, \dots, Y_n\}} [X_1 \mapsto Y_1, \dots, X_n \mapsto Y_n]C} \text{ CT-Var} \end{split}$$

Example

Interaction with Side Effects



Example

Let-polymorphism would assign $\forall X$. Ref $(X \to X)$ to Γ in the following code:

```
let r = ref (λx:X. x) in
(r:= (λx:Nat. succ x);
  (!r)true);
```

When type-checking the second line, we instantiate r to have type $Ref(Nat \rightarrow Nat)$. When type-checking the third line, we instantiate r to have type $Ref(Bool \rightarrow Bool)$. But this is unsound!

Value Restriction

A let-binding can be treated polymorphically—i.e., its free type variables can be generalized—only if its right-hand side is a **syntactic value**.

Homework



Question

Consider the following lambda-abstraction:

$$\lambda x:X. \times X$$

Construct a constraint typing derivation for it.

Is the constraint set unifiable?

What if removing the occur checks in the *unify* algorithm and allowing recursive types, as shown below? What is the result of this *unify* algorithm?

```
\begin{array}{ll} \textit{unify}(C) &=& \dots \\ & \text{else if } S = X \text{ and } X \not\in \mathit{FV}(T) \\ & \text{then } \mathit{unify}([X \mapsto T]C') \circ [X \mapsto T] \\ & \text{else if } S = X \text{ and } X \in \mathit{FV}(T) \\ & \text{then } \mathit{unify}([X \mapsto \mu X.\,T]C') \circ [X \mapsto \mu X.\,T] \\ & \dots \end{array}
```