



编程语言的设计原理

Design Principles of Programming Languages

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Issues in Subtyping



Typing with Subsumption

Principle of safe substitution:

– *a value of one* can *always safely be used* where *a value of the other* is expected

1. a *subtyping relation* between types, written $S <: T$
2. a rule of *subsumption* stating that, if $S <: T$, then any value of type S can also be regarded as having type T , i.e.,

$$\frac{\Gamma \vdash t : S \quad S <: T}{\Gamma \vdash t : T} \quad (\text{T-SUB})$$



Issues in Subtyping

For a *given subtyping statement*, there are *multiple rules* that could be used in a derivation.

1. The conclusions of *S-RcdWidth*, *S-RcdDepth*, and *S-RcdPerm* *overlap with each other*.
2. *S-REFL* and *S-TRANS* overlap with *every other rule*.

$$S <: S \quad (\text{S-REFL})$$

$$\frac{S <: U \quad U <: T}{S <: T} \quad (\text{S-TRANS})$$



Syntax-directed rules

In the simply typed lambda-calculus (without subtyping), *each rule* can be “*read from bottom to top*” in a straightforward way.

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11}}{\Gamma \vdash t_1 t_2 : T_{12}} \quad (\text{T-APP})$$

If we are given some Γ and some t of the form $t_1 t_2$, we can try to *find a type* for t by

1. finding (recursively) a type for t_1
2. checking that it has the form $T_{11} \rightarrow T_{12}$
3. finding (recursively) a type for t_2
4. checking that it is the same as T_{11}



Syntax-directed rules

The first reason this works is that we can *divide* the “**positions**” of the typing relation $(\Gamma \vdash t : T)$ into **input positions** (i.e., Γ and t) and **output positions** (T).

- For the input positions, **all metavariables** appearing in the *premises* also appear in the *conclusion* (so we can calculate inputs to the “sub-goals” from the sub-expressions of inputs to the main goal)
- For the output positions, **all metavariables** appearing in the *conclusions* also appear in the *premises* (so we can calculate outputs from the main goal from the outputs of the subgoals)

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11}}{\Gamma \vdash t_1 \ t_2 : T_{12}} \quad (\text{T-APP})$$



Syntax-directed sets of rules

The *second important point* about the simply typed lambda-calculus is that *the set of typing rules is syntax-directed*:

- For every “**input**” Γ and t , there is **exactly one rule** that can be used to derive typing statements involving t , e.g.,
 - if t is an *application*, then we must proceed by trying to use **T-APP**
- If we succeed, then we have found **a type** (indeed, the *unique type*) for t
- If it **fails**, then we know that t is **not typable**

⇒ no backtracking!



Non-syntax-directedness of typing

When the system is extended with *subtyping*, both aspects of syntax-directedness get broken.

1. The set of typing rules now includes *two rules* that can be used to give a type to terms of a given shape (*the old one* + T-SUB)

$$\frac{\Gamma \vdash t : S \quad S <: T}{\Gamma \vdash t : T} \quad (\text{T-SUB})$$

2. Worse yet, the new rule T-SUB *itself is not syntax directed*: the *inputs* to *the left-hand sub-goal are exactly the same* as the *inputs* to *the main goal*

Hence, if we translate the typing rules naively into a typechecking function, the case corresponding to T-SUB would cause *divergence*



Non-syntax-directedness of subtyping

Moreover, the *subtyping relation* is *not syntax directed* either

1. There are *lots of ways* to derive a given subtyping statement
(\because 8.2.4 /9.3.3 [uniqueness of types] \times)
2. The transitivity rule

$$\frac{S <: U \quad U <: T}{S <: T} \quad (\text{S-TRANS})$$

is *badly non-syntax-directed*: the premises contain a *metavariable* (in an “*input position*”) that does *not appear at all in the conclusion*.

To implement this rule naively, we have to *guess* a value for **U**!



What to do?

Turn the *declarative version* of subtyping into the *algorithmic version*

The **problem** was that

we don't have an algorithm to decide when $S <: T$ or $\Gamma \vdash t : T$

Both sets of rules are not *syntax-directed*



Chap 16

Metatheory of Subtyping

Algorithmic Subtyping

Algorithmic Typing

Joins and Meets



Developing an algorithmic subtyping relation



Algorithmic Subtyping



What to do

How do we change the rules deriving $S <: T$ to be *syntax-directed*?

There are lots of ways to derive a given subtyping statement $S <: T$.

The general idea is to *change this system* so that there is ***only one way*** to derive it.



Step 1: simplify record subtyping

Idea: combine *all three record subtyping rules* into one “*macro rule*” that captures all of their effects

$$\frac{\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\} \quad k_j = l_i \text{ implies } S_j <: T_i}{\{k_j: S_j^{j \in 1..m}\} <: \{l_i: T_i^{i \in 1..n}\}} \quad (\text{S-RCD})$$

Lemma 16.1.1: If $S <: T$ is derivable from the subtyping rules including **S-RcdDepth**, **S-Rcd-Width**, and **S-Rcd-Perm** (but not **S-Rcd**), then it can also be derived using **S-Rcd** (and not **S-RcdDepth**, **S-Rcd-Width**, or **S-Rcd-Perm**), and vice versa.



Simpler subtype relation

$$S <: S \quad (\text{S-REFL})$$

$$\frac{S <: U \quad U <: T}{S <: T} \quad (\text{S-TRANS})$$

$$\frac{\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\} \quad k_j = l_i \text{ implies } S_j <: T_i}{\{k_j : S_j^{j \in 1..m}\} <: \{l_i : T_i^{i \in 1..n}\}} \quad (\text{S-RCD})$$

$$\frac{T_1 <: S_1 \quad S_2 <: T_2}{S_1 \rightarrow S_2 <: T_1 \rightarrow T_2} \quad (\text{S-ARROW})$$

$$S <: \text{Top} \quad (\text{S-TOP})$$



Step 2: Get rid of reflexivity

Observation: S -REFL is unnecessary.

Lemma 16.1.2: $S <: S$ can be derived for every type S without using S -REFL.



Even simpler subtype relation

$$\frac{S <: U \quad U <: T}{S <: T} \quad (\text{S-TRANS})$$

$$\frac{\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\} \quad k_j = l_i \text{ implies } S_j <: T_i}{\{k_j : S_j^{j \in 1..m}\} <: \{l_i : T_i^{i \in 1..n}\}} \quad (\text{S-RCD})$$

$$\frac{T_1 <: S_1 \quad S_2 <: T_2}{S_1 \rightarrow S_2 <: T_1 \rightarrow T_2} \quad (\text{S-ARROW})$$

$$S <: \text{Top} \quad (\text{S-TOP})$$



Step 3: Get rid of transitivity

Observation: S-Trans is unnecessary.

Lemma 16.1.2: If $S <: T$ can be derived, then it can be derived without using S-Trans.



Even simpler subtype relation

$$\frac{\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\} \quad k_j = l_i \text{ implies } S_j <: T_i}{\{k_j : S_j^{j \in 1..m}\} <: \{l_i : T_i^{i \in 1..n}\}} \quad (\text{S-RCD})$$

$$\frac{T_1 <: S_1 \quad S_2 <: T_2}{S_1 \rightarrow S_2 <: T_1 \rightarrow T_2} \quad (\text{S-ARROW})$$

$$S <: \text{Top} \quad (\text{S-TOP})$$



“Algorithmic” subtype relation

Definition: The *algorithmic subtyping relation* is the least relation on types closed under the following 3 rules

$$\boxed{\vdash} S <: \text{Top} \quad (\boxed{\text{SA}}\text{-TOP})$$

$$\frac{\vdash T_1 <: S_1 \quad \vdash S_2 <: T_2}{\vdash S_1 \rightarrow S_2 <: T_1 \rightarrow T_2} \quad (\text{SA-ARROW})$$

$$\frac{\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\} \quad \text{for each } k_j = l_i, \vdash S_j <: T_i}{\vdash \{k_j : S_j^{j \in 1..m}\} <: \{l_i : T_i^{i \in 1..n}\}} \quad (\text{SA-RCD})$$



Soundness and completeness

Theorem[16.1.5]: $S <: T$ iff $\mapsto S <: T$

Terminology:

- The *algorithmic presentation* of subtyping is *sound* with respect to the original, if $\mapsto S <: T$ implies $S <: T$
(*Everything validated by the algorithm is actually true*)
- The *algorithmic presentation* of subtyping is *complete* with respect to the original, if $S <: T$ implies $\mapsto S <: T$
(*Everything true is validated by the algorithm*)



Subtyping Algorithm

$subtype(S, T) =$

if $T = \text{Top}$, then *true*

else if $S = S_1 \rightarrow S_2$ and $T = T_1 \rightarrow T_2$

then $subtype(T_1, S_1) \wedge subtype(S_2, T_2)$

else if $S = \{k_j: S_j^{j \in 1..m}\}$ and $T = \{l_i: T_i^{i \in 1..n}\}$

then $\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\} \wedge$

for all $i \in 1..n$ there is some $j \in 1..m$ with $k_j = l_i$ and $subtype(S_j, T_i)$

else *false*.



Decision Procedures

Recall: A decision procedure for a relation $R \subseteq U$ is *a total function* p from U to $\{true, false\}$ such that $p(u) = true$ iff $u \in R$.

Is our *subtype* function a decision procedure?

subtype is just *an implementation of the algorithmic subtyping rules*, we have

1. if $subtype(S, T) = true$, then $\mapsto S <: T$
hence, by *soundness* of the algorithmic rules, $S <: T$
2. if $subtype(S, T) = false$, then $\text{not } \mapsto S <: T$
hence, by *completeness* of the algorithmic rules, $\text{not } S <: T$

Q: *What's missing?*

Decision Procedures

Is our *subtype* function a decision procedure?

Since *subtype* is just **an implementation of the algorithmic subtyping rules**, we have

1. if $subtype(S, T) = true$, then $\mapsto S <: T$
(hence, by **soundness** of the algorithmic rules, $S <: T$)
1. if $subtype(S, T) = false$, then not $\mapsto S <: T$
(hence, by **completeness** of the algorithmic rules, not $S <: T$)

Q: **What's missing?**

A: How do we know that *subtype* is a **total function**?



Decision Procedures

Is our *subtype* function a decision procedure?

Since *subtype* is just **an implementation of the algorithmic subtyping rules**, we have

1. if $subtype(S, T) = true$, then $\mapsto S <: T$
(hence, by **soundness** of the algorithmic rules, $S <: T$)
1. if $subtype(S, T) = false$, then not $\mapsto S <: T$
(hence, by **completeness** of the algorithmic rules, not $S <: T$)

Q: **What's missing?**

A: How do we know that ***subtype is a total function?***

Prove it!



Decision Procedures

Recall: A decision procedure for a relation $R \subseteq U$ is *a total function* p from U to $\{true, false\}$ such that $p(u) = true$ iff $u \in R$.

Example:

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$



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The function p' whose graph is

$$\{((1, 2), true), ((2, 3), true)\}$$

is not a decision function for R

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Example:

$$U = \{1, 2, 3\}$$

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The function p'' whose graph is

$$\{((1, 2), true), ((2, 3), true), ((1, 3), false)\}$$

is also not a decision function for R



Decision Procedures

Recall: A decision procedure for a relation $R \subseteq U$ is *a total function* p from U to $\{true, false\}$ such that $p(u) = true$ iff $u \in R$.

Example:

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The function p whose graph is

$$\begin{aligned} &\{ ((1, 2), true), ((2, 3), true), \\ &\quad ((1, 1), false), ((1, 3), false), \\ &\quad ((2, 1), false), ((2, 2), false), \\ &\quad ((3, 1), false), ((3, 2), false), ((3, 3), false) \} \end{aligned}$$

is a decision function for R



Decision Procedures (take 2)

We want *a decision procedure* to be a *procedure*.

A *decision procedure* for a relation $R \subseteq U$ is a **computable total function** p from U to $\{true, false\}$ such that

$$p(u) = true \text{ iff } u \in R.$$

Example

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The function

$$p(x, y) = \begin{array}{l} \text{if } x = 2 \text{ and } y = 3 \text{ then true} \\ \text{else if } x = 1 \text{ and } y = 2 \text{ then true} \\ \text{else false} \end{array}$$

whose graph is

$$\begin{array}{l} \{ ((1, 2), \text{true}), ((2, 3), \text{true}), \\ ((1, 1), \text{false}), ((1, 3), \text{false}), \\ ((2, 1), \text{false}), ((2, 2), \text{false}), \\ ((3, 1), \text{false}), ((3, 2), \text{false}), ((3, 3), \text{false}) \} \end{array}$$

is a decision procedure for R .

Example

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The recursively defined *partial function*

$$p(x, y) = \begin{array}{l} \text{if } x = 2 \text{ and } y = 3 \text{ then true} \\ \text{else if } x = 1 \text{ and } y = 2 \text{ then true} \\ \text{else if } x = 1 \text{ and } y = 3 \text{ then false} \\ \text{else } p(x, y) \end{array}$$

whose graph is

$$\{((1, 2), \text{true}), ((2, 3), \text{true}), ((1, 3), \text{false})\}$$

is *not* a decision procedure for R .



Subtyping Algorithm

The following *recursively defined total function* is a *decision procedure* for the subtype relation:

$subtype(S, T) =$

if $T = \text{Top}$ then *true*

else if $S = S_1 \rightarrow S_2$ and $T = T_1 \rightarrow T_2$

then $subtype(T_1, S_1) \wedge subtype(S_2, T_2)$

else if $S = \{k_j: S_j^{j \in 1..m}\}$ and $T = \{l_i: T_i^{i \in 1..n}\}$

then $\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\} \wedge$

for all $i \in 1..n$ there is some $j \in 1..m$ with $k_j = l_i$ and $subtype(S_j, T_i)$

else *false*.



Subtyping Algorithm

This *recursively defined total function* is a decision procedure for the subtype relation:

$subtype(S, T) =$
if $T = \text{Top}$ then *true*
else if $S = S_1 \rightarrow S_2$ and $T = T_1 \rightarrow T_2$
then $subtype(T_1, S_1) \wedge subtype(S_2, T_2)$
else if $S = \{k_j: S_j^{j \in 1..m}\}$ and $T = \{l_i: T_i^{i \in 1..n}\}$
then $\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\} \wedge$
for all $i \in 1..n$ there is some $j \in 1..m$ with $k_j = l_i$ and $subtype(S_j, T_i)$
else *false*.

To show this, we *need to prove* :

1. that it returns *true* whenever $S <: T$, and
2. that it returns either *true* or *false* on *all inputs*

[16.1.6 Termination Proposition]



Algorithmic Typing



Algorithmic typing

How do we implement a *type checker* for the lambda-calculus *with subtyping*?

Given a context Γ and a term t , how do we determine its type T , such that $\Gamma \vdash t : T$?



Issue

For the typing relation, we have *just one problematic rule* to deal with: *subsumption rule*

$$\frac{\Gamma \vdash t : S \quad S <: T}{\Gamma \vdash t : T} \quad (\text{T-SUB})$$

Q: where is this rule really needed?

For *applications*, e.g., the term $(\lambda r: \{x: \text{Nat}\}. r. x) \{x = 0, y = 1\}$ is *not typable* without using subsumption.

Where else??

Nowhere else!

Uses of subsumption rule to help typecheck *applications* are the only interesting ones (where subsumption plays a crucial role in typing)



Plan

1. Investigate *how subsumption is used* in typing derivations by *looking at examples* of how it can be “*pushed through*” other rules;
2. Use the intuitions gained from these examples to design a new, algorithmic typing relation that
 - *Omits subsumption;*
 - Compensates for its absence by *enriching the application rule;*
3. Show that the *algorithmic typing relation* is essentially *equivalent* to the original, *declarative one*.

Example (T-ABS)



$$\begin{array}{c}
 \vdots \qquad \qquad \qquad \vdots \\
 \hline
 \Gamma, x:S_1 \vdash s_2 : S_2 \qquad S_2 <: T_2 \\
 \hline
 \Gamma, x:S_1 \vdash s_2 : T_2 \qquad \text{(T-SUB)} \\
 \hline
 \Gamma \vdash \lambda x:S_1. s_2 : S_1 \rightarrow T_2 \qquad \text{(T-ABS)}
 \end{array}$$

becomes

$$\begin{array}{c}
 \vdots \qquad \qquad \qquad \vdots \\
 \hline
 \Gamma, x:S_1 \vdash s_2 : S_2 \qquad S_1 <: S_1 \qquad S_2 <: T_2 \\
 \hline
 \Gamma \vdash \lambda x:S_1. s_2 : S_1 \rightarrow S_2 \qquad S_1 \rightarrow S_2 <: S_1 \rightarrow T_2 \qquad \text{(S-REFL)} \qquad \text{(S-ARROW)} \\
 \hline
 \Gamma \vdash \lambda x:S_1. s_2 : S_1 \rightarrow T_2 \qquad \text{(T-SUB)}
 \end{array}$$



Intuitions

These examples show that *we do not need T-SUB to “enable” T-ABS* :

- given any typing derivation, we **can construct a derivation** *with the same conclusion* in which **T-SUB** is never used immediately before **T-ABS**.

What about **T-APP**?

We’ve already observed that **T-SUB** is required for typechecking some *applications*

Therefore we expect to find that we **cannot play the same game** with **T-APP** as we’ve done with **T-ABS**

Let’s see why.

Example (T-Sub with T-APP on the right)

$$\frac{\frac{\vdots}{\Gamma \vdash s_1 : T_{11} \rightarrow T_{12}} \quad \frac{\frac{\vdots}{\Gamma \vdash s_2 : T_2} \quad T_2 <: T_{11}}{\Gamma \vdash s_2 : T_{11}} \text{ (T-SUB)}}{\Gamma \vdash s_1 s_2 : T_{12}} \text{ (T-APP)}$$

becomes

$$\frac{\frac{\frac{\vdots}{\Gamma \vdash s_1 : T_{11} \rightarrow T_{12}} \quad \frac{\frac{\vdots}{T_2 <: T_{11}} \quad T_{12} <: T_{12}}{T_{11} \rightarrow T_{12} <: T_2 \rightarrow T_{12}} \text{ (S-REFL)}}{\Gamma \vdash s_1 : T_2 \rightarrow T_{12}} \text{ (S-ARROW)} \quad \frac{\vdots}{\Gamma \vdash s_2 : T_2}}{\Gamma \vdash s_1 s_2 : T_{12}} \text{ (T-APP)}$$



Observations

We've seen that ***uses of subsumption rule*** can be “*pushed*” from one of immediately before T-APP's premises to the other, but ***cannot be completely eliminated***



Example (nested uses of T-Sub)

$$\frac{\frac{\frac{\vdots}{\Gamma \vdash s : S} \quad \frac{\frac{\vdots}{S <: U}}{\Gamma \vdash s : U} \text{ (T-SUB)}}{\Gamma \vdash s : U} \quad \frac{\frac{\vdots}{U <: T}}{\Gamma \vdash s : T} \text{ (T-SUB)}}{\Gamma \vdash s : T} \text{ (T-SUB)}$$

becomes

$$\frac{\frac{\frac{\vdots}{\Gamma \vdash s : S} \quad \frac{\frac{\frac{\vdots}{S <: U} \quad \frac{\frac{\vdots}{U <: T}}{S <: T} \text{ (S-TRANS)}}{\Gamma \vdash s : S} \quad S <: T}{\Gamma \vdash s : T} \text{ (T-SUB)}}{\Gamma \vdash s : T} \text{ (T-SUB)}$$

Summary

What we've learned:

- **Uses of the T-Sub** rule can be “*pushed down*” through typing derivations until they encounter **either**
 1. a use at the end of right-hand subderivations of **T-App**, **or**
 2. the **root** of the derivation tree (the **very end of the whole derivation**)
- In both cases, **multiple uses of T-Sub can be coalesced into a single one.**

This suggests a notion of “*normal form*” for typing derivations, in which there is

- **exactly one use** of **T-Sub** before each use of **T-App**,
- **one use** of **T-Sub** at **the very end** of the derivation,
- no uses of **T-Sub** anywhere else.

Algorithmic Typing

The next step is to “build in” the use of subsumption rule in *application rules*, by *changing* the T-App rule to *incorporate a subtyping premise*

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_2 \quad \boxed{\vdash T_2 <: T_{11}}}{\Gamma \vdash t_1 t_2 : T_{12}}$$

Given any typing derivation, we can now

1. *normalize* it, to *move all uses of subsumption rule* to either just *before applications* (in the right-hand premise) or *at the very end*
2. *replace* uses of T-App with T-SUB in the right-hand premise by uses of the extended rule above

This yields a derivation in which there is *just one use of subsumption*, at the very end!



Minimal Types

But... if subsumption is only used at the very end of derivations, then it is actually *not needed* in order to show that *any term is typable*!

It is just used to give *more* types to terms that have already been shown to have a type.

In other words, if we *dropped subsumption completely* (after refining the application rule), we would still be able to give types to exactly the same set of terms — we just would not be able to give as *many types* to some of them.

If we drop subsumption, then the remaining rules will assign a *unique, minimal* type to *each typable term*

For purposes of building a typechecking algorithm, this is enough



Final Algorithmic Typing Rules

$$\frac{x:T \in \Gamma}{\Gamma \vdash x : T} \quad (\text{TA-VAR})$$

$$\frac{\Gamma, x:T_1 \vdash t_2 : T_2}{\Gamma \vdash \lambda x:T_1. t_2 : T_1 \rightarrow T_2} \quad (\text{TA-ABS})$$

$$\frac{\Gamma \vdash t_1 : T_1 \quad T_1 = T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_2 \quad \boxed{\vdash T_2 <: T_{11}}}{\Gamma \vdash t_1 t_2 : T_{12}} \quad (\text{TA-APP})$$

$$\frac{\text{for each } i \quad \Gamma \vdash t_i : T_i}{\Gamma \vdash \{l_1=t_1 \dots l_n=t_n\} : \{l_1:T_1 \dots l_n:T_n\}} \quad (\text{TA-RCD})$$

$$\frac{\Gamma \vdash t_1 : R_1 \quad R_1 = \{l_1:T_1 \dots l_n:T_n\}}{\Gamma \vdash t_1.l_j : T_j} \quad (\text{TA-PROJ})$$



Completeness of the algorithmic rules

Theorem [Minimal Typing]:

If $\Gamma \vdash t : T$, then $\Gamma \mapsto t : S$ for some $S <: T$.

Proof: Induction on *typing derivation*.

N.b.: All the messing around with transforming derivations was just to build intuitions and *decide what algorithmic rules* to write down and *what property to prove*:

the proof itself is *a straightforward induction on typing derivations*.



Meets and Joins



Adding Booleans

Suppose we want to add *booleans* and *conditionals* to the language we have been discussing.

For the declarative presentation of the system, we just add in the appropriate *syntactic forms*, *evaluation rules*, and *typing rules*.

$$\begin{array}{l} \Gamma \vdash \text{true} : \text{Bool} \qquad \qquad \qquad (\text{T-TRUE}) \\ \Gamma \vdash \text{false} : \text{Bool} \qquad \qquad \qquad (\text{T-FALSE}) \\ \hline \frac{\Gamma \vdash t_1 : \text{Bool} \quad \Gamma \vdash t_2 : T \quad \Gamma \vdash t_3 : T}{\Gamma \vdash \text{if } t_1 \text{ then } t_2 \text{ else } t_3 : T} \qquad (\text{T-IF}) \end{array}$$



A Problem with Conditional Expressions

For the *algorithmic presentation* of the system, however, we encounter a little difficulty.

What is the minimal type of

if true then {x = true, y = false} else {x = true, z = true} ?

The Algorithmic Conditional Rule

More generally, we can use subsumption to give an expression

$\text{if } t_1 \text{ then } t_2 \text{ else } t_3$

any type that is a possible type of both t_2 and t_3 .

So the *minimal type* of the *conditional* is the

least common supertype (or *join*) of

the minimal type of t_2 and the minimal type of t_3

$$\frac{\Gamma \vdash t_1 : \text{Bool} \quad \Gamma \vdash t_2 : T_2 \quad \Gamma \vdash t_3 : T_3}{\Gamma \vdash \text{if } t_1 \text{ then } t_2 \text{ else } t_3 : T_2 \vee T_3} \quad (\text{T-IF})$$

Q: Does such a type exist for every T_2 and T_3 ??



Existence of Joins

Theorem: For every pair of types S and T , there is a type J such that

1. $S <: J$
2. $T <: J$
3. If K is a type such that $S <: K$ and $T <: K$, then $J <: K$.

i.e., J is the *smallest type* that is a supertype of both S and T .

How to prove it?

Calculating Joins



$$S \vee T = \begin{cases} \text{Bool} & \text{if } S = T = \text{Bool} \\ M_1 \rightarrow J_2 & \text{if } S = S_1 \rightarrow S_2 \quad T = T_1 \rightarrow T_2 \\ & S_1 \wedge T_1 = M_1 \quad S_2 \vee T_2 = J_2 \\ \{j_l : J_l \mid l \in 1..q\} & \text{if } S = \{k_j : S_j \mid j \in 1..m\} \\ & T = \{l_i : T_i \mid i \in 1..n\} \\ & \{j_l \mid l \in 1..q\} = \{k_j \mid j \in 1..m\} \cap \{l_i \mid i \in 1..n\} \\ & S_j \vee T_i = J_l \quad \text{for each } j_l = k_j = l_i \\ \text{Top} & \text{otherwise} \end{cases}$$

Examples

What are the joins of the following pairs of types?

1. $\{x: \text{Bool}, y: \text{Bool}\}$ and $\{y: \text{Bool}, z: \text{Bool}\}$?
2. $\{x: \text{Bool}\}$ and $\{y: \text{Bool}\}$?
3. $\{x: \{a: \text{Bool}, b: \text{Bool}\}\}$ and $\{x: \{b: \text{Bool}, c: \text{Bool}\}, y: \text{Bool}\}$?
4. $\{\}$ and Bool ?
5. $\{x: \{\}\}$ and $\{x: \text{Bool}\}$?
6. $\text{Top} \rightarrow \{x: \text{Bool}\}$ and $\text{Top} \rightarrow \{y: \text{Bool}\}$?
7. $\{x: \text{Bool}\} \rightarrow \text{Top}$ and $\{y: \text{Bool}\} \rightarrow \text{Top}$?

Meets

$$S \vee T = \begin{cases} \text{Bool} & \text{if } S = T = \text{Bool} \\ M_1 \rightarrow J_2 & \text{if } S = S_1 \rightarrow S_2 \quad T = T_1 \rightarrow T_2 \\ & \quad \underline{S_1 \wedge T_1 = M_1} \quad S_2 \vee T_2 = J_2 \\ \{j_l : J_l \mid l \in 1..q\} & \text{if } S = \{k_j : S_j \mid j \in 1..m\} \\ & \quad T = \{l_i : T_i \mid i \in 1..n\} \\ & \quad \{j_l \mid l \in 1..q\} = \{k_j \mid j \in 1..m\} \cap \{l_i \mid i \in 1..n\} \\ & \quad S_j \vee T_i = J_l \quad \text{for each } j_l = k_j = l_i \\ \text{Top} & \text{otherwise} \end{cases}$$

To calculate joins of arrow types, we also need to be able to calculate **meets** (greatest lower bounds)!

Unlike joins, meets *do not necessarily exist*

- e.g., $\text{Bool} \rightarrow \text{Bool}$ and $\{\}$ have *no common subtypes*, so they certainly don't have a greatest one!

Existence of Meets

Theorem: For every pair of types S and T , we say that a type M is a meet of S and T , written $S \wedge T = M$ if

1. $M <: S$
2. $M <: T$
3. If O is a type such that $O <: S$ and $O <: T$, then $O <: M$.

i.e., M (when it exists) is the *largest type* that is a subtype of both S and T .

Jargon: In the simply typed lambda calculus with subtyping, records, and booleans ...

- The subtype relation *has joins*
- The subtype relation *has bounded meets*

Calculating Meets

$S \wedge T =$

{	S	if $T = \text{Top}$
	T	if $S = \text{Top}$
	Bool	if $S = T = \text{Bool}$
	$J_1 \rightarrow M_2$	if $S = S_1 \rightarrow S_2$ $T = T_1 \rightarrow T_2$ $S_1 \vee T_1 = J_1$ $S_2 \wedge T_2 = M_2$
	$\{m_l : M_l \mid l \in 1..q\}$	if $S = \{k_j : S_j \mid j \in 1..m\}$ $T = \{l_i : T_i \mid i \in 1..n\}$ $\{m_l \mid l \in 1..q\} = \{k_j \mid j \in 1..m\} \cup \{l_i \mid i \in 1..n\}$ $S_j \wedge T_i = M_l$ for each $m_l = k_j = l_i$ $M_l = S_j$ if $m_l = k_j$ occurs only in S $M_l = T_i$ if $m_l = l_i$ occurs only in T
	fail	otherwise



Examples

What are the meets of the following pairs of types?

1. $\{x: \text{Bool}, y: \text{Bool}\}$ and $\{y: \text{Bool}, z: \text{Bool}\}$?
2. $\{x: \text{Bool}\}$ and $\{y: \text{Bool}\}$?
3. $\{x: \{a: \text{Bool}, b: \text{Bool}\}\}$ and $\{x: \{b: \text{Bool}, c: \text{Bool}\}, y: \text{Bool}\}$?
4. $\{\}$ and Bool ?
5. $\{x: \{\}\}$ and $\{x: \text{Bool}\}$?
6. $\text{Top} \rightarrow \{x: \text{Bool}\}$ and $\text{Top} \rightarrow \{y: \text{Bool}\}$?
7. $\{x: \text{Bool}\} \rightarrow \text{Top}$ and $\{y: \text{Bool}\} \rightarrow \text{Top}$?



Homework😊

- Read and digest chapter 16 & 17
- HW:
 - 16.1.3;
 - 16.2.6;