



编程语言的设计原理

Design Principles of Programming Languages

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Recap: untyped lambda-calculus

Syntax

$t ::=$

x

$\lambda x. t$

$t t$

$v ::=$

$\lambda x. t$

terms:

variable

abstraction

application

values:

abstraction value

Evaluation

$t \rightarrow t'$

$$\frac{t_1 \rightarrow t'_1}{t_1 t_2 \rightarrow t'_1 t_2}$$

(E-APP1)

$$\frac{t_2 \rightarrow t'_2}{v_1 t_2 \rightarrow v_1 t'_2}$$

(E-APP2)

$$(\lambda x. t_{12}) v_2 \rightarrow [x \mapsto v_2] t_{12} \quad \text{(E-APPABS)}$$

- The λ -calculus embodies this kind of *function definition* and *application* in the purest possible form
 - terms in the pure λ -calculus are often called λ -terms
 - terms of the form $\lambda x. t$ are called λ -abstractions or just abstractions



Syntax

- **Definition [Terms]:**

Let \mathcal{V} be a *countable set* of variable names.

The set of terms is *the smallest set* \mathcal{T} such that

1. $x \in \mathcal{T}$ for every $x \in \mathcal{V}$;
2. if $t_1 \in \mathcal{T}$ and $x \in \mathcal{V}$, then $\lambda x.t_1 \in \mathcal{T}$;
3. if $t_1 \in \mathcal{T}$ and $t_2 \in \mathcal{T}$, then $t_1 t_2 \in \mathcal{T}$.



Syntactic conventions

- The λ -calculus provides *only one-argument functions*, all multi-argument functions must be written in *curried style*.
- The following *conventions* make the linear forms of terms easier to read and write:
 - **Application binds more tightly than abstraction**
e.g., $\lambda x. x y$ means $\lambda x. (x y)$ not $(\lambda x. x) y$
 - **Application associates to the left**
e.g., $t u v$ means $(t u) v$, not $t (u v)$
 - **Bodies of λ -abstractions extend as far to the right as possible**
e.g., $\lambda x. \lambda y. x y$ means $\lambda x. (\lambda y. x y)$, not $\lambda x. (\lambda y. x) y$

Scope

- *An occurrence* of the variable x is said to be *bound* when it occurs in the body t of an abstraction $\lambda x.t$, i.e.,
 - the λ -abstraction term $\lambda x.t$ binds the variable x , and **the scope** of this binding is **the body** t .
 - λx is a *binder* (binding construct) whose *scope* is t .
 - e.g., $(\lambda x.(\lambda y.x y)) y$
 - a binder can be *renamed* as necessary
 - so-called: *alpha-renaming/ alpha-conversion*
 - e.g., $\lambda x.x = \lambda y.y$



Scope

- **Definition:** Free Variables of term t , written as $FV(t)$:

$$FV(x) = \{x\}$$

$$FV(\lambda x.t_1) = FV(t_1) \setminus \{x\}$$

$$FV(t_1 t_2) = FV(t_1) \cup FV(t_2)$$



Operational Semantics

- Computation rule

$$(\lambda x. t_{12}) v_2 \longrightarrow [x \mapsto v_2]t_{12} \quad (\text{E-APPABS})$$

- Congruence rules

$$\frac{t_1 \longrightarrow t'_1}{t_1 t_2 \longrightarrow t'_1 t_2} \quad (\text{E-APP1})$$

$$\frac{t_2 \longrightarrow t'_2}{v_1 t_2 \longrightarrow v_1 t'_2} \quad (\text{E-APP2})$$

Operational Semantics

- *Beta-reduction*: the only computation (**substitution**)

$$(\lambda x. t_{12}) t_2 \rightarrow [x \mapsto t_2] t_{12},$$

- the term obtained by *replacing all free occurrences* of x in t_{12} by t_2
 - a *redex* (short for “*reducible expression*”) : a term of the form $(\lambda x. t) v$ — a *λ -abstraction* applied to a *value*
 - the operation of rewriting a *redex* according to the above rule is called *beta-reduction*
- Examples:

$$(\lambda x. x) y \rightarrow y$$

$$(\lambda x. x (\lambda x. x)) (u r) \rightarrow u r (\lambda x. x)$$



Substitution

$$[x \mapsto s]x = s$$

$$[x \mapsto s]y = y \quad \text{if } y \neq x$$

$$[x \mapsto s](\lambda y. t_1) = \lambda y. [x \mapsto s]t_1 \quad \text{if } y \neq x \text{ and } y \notin FV(s)$$

$$[x \mapsto s](t_1 t_2) = [x \mapsto s]t_1 [x \mapsto s]t_2$$

Alpha-conversion : Terms that **differ only in the names of bound variables** are **interchangeable** in all contexts.

Example:

$$\begin{aligned} & [x \mapsto y z] (\lambda y. x y) \\ &= [x \mapsto y z] (\lambda w. x w) \\ &= \lambda w. y z w \end{aligned}$$

Bound Variables

- Recall that bound variables **can be renamed, at any moment**, to enable substitution:

$$[x \mapsto s]x = s$$

$$[x \mapsto s]y = y \quad \text{if } y \neq x$$

$$[x \mapsto s](\lambda y. t_1) = \lambda y. [x \mapsto s]t_1 \quad \text{if } y \neq x \text{ and } y \notin FV(s)$$

$$[x \mapsto s](t_1 t_2) = [x \mapsto s]t_1 [x \mapsto s]t_2$$

- Variable Representation
 - Represent variables symbolically, with variable renaming mechanism
 - Represent variables symbolically, with bound variables are all different from each other and from any free variable
 - **“Canonically” represent variables in a way such that renaming is unnecessary**
 - No use of variables: combinatory logic, or something like Backus’ functional language FP



Chapter 6

Nameless Representation of Terms

Terms and Contexts

Shifting and Substitution



Terms and Contexts



Nameless Terms

- *De Bruijn* idea: Replacing named variables by *natural numbers*, where the number k stands for “the variable bound by the k 'th enclosing λ ”.
- 1. **Index Starts at 0** : The count begins at 0 for the nearest enclosing lambda.
- 2. **Each λ Adds a Level**: Traversing a lambda increases the binding depth by 1.
- 3. **Count Upwards**: The index of a variable is the number of lambdas you encounter when moving up the term tree until you reach its binder.

• e.g.,

– $\lambda x.x$	$\lambda.0$
– $\lambda x.\lambda y.x$	$\lambda.\lambda.1$
– $\lambda x.\lambda y.y$	$\lambda.\lambda.0$
– $\lambda x.\lambda y. x (y x)$	$\lambda.\lambda.1 (0 1)$
– $(\lambda x. x) (\lambda y. y)$	$(\lambda 0) (\lambda 0)$

De Bruijn indices vs *De Bruijn terms/nameless terms*



Nameless Terms

- *De Bruijn* idea: Replacing named variables by *natural numbers*, where the number k stands for “the variable bound by the k 'th enclosing λ ”.
- e.g., the corresponding nameless term for the following:
 $c0 = \lambda s. \lambda z. z;$
 $c2 = \lambda s. \lambda z. s (s z);$
plus = $\lambda m. \lambda n. \lambda s. \lambda z. m s (n z s);$
fix = $\lambda f. (\lambda x. f (\lambda y. (x x) y)) (\lambda x. f (\lambda y. (x x) y));$
foo = $(\lambda x. (\lambda x. x)) (\lambda x. x);$



Nameless Terms

- Need to keep track of how many free variables each term may contain.

Definition [Terms]: Let \mathcal{T} be *the smallest family of sets* $\{\mathcal{T}_0, \mathcal{T}_1, \mathcal{T}_2, \dots\}$ such that

1. $k \in \mathcal{T}_n$ whenever $0 \leq k < n$;
2. if $t_1 \in \mathcal{T}_n$ and $n > 0$, then $\lambda.t_1 \in \mathcal{T}_{n-1}$;
3. if $t_1 \in \mathcal{T}_n$ and $t_2 \in \mathcal{T}_n$, then $(t_1 t_2) \in \mathcal{T}_n$.

- **Note:**

- terms with **no free variables** are called the **0-terms**; **1-terms (one free variables)**, ...
- \mathcal{T}_n are set of terms with **at most n** free variables, **n-terms**, numbered between **0** and **n-1**: a given element of \mathcal{T}_n need not have free variables with all these numbers, or indeed any free variables at all. When t is closed, for example, it will be an element of \mathcal{T}_n for every n .
- two ordinary terms are *equivalent modulo renaming of bound variables* iff they have the **same de Bruijn representation**.



Name Context

How to represent

$$\lambda x. y x$$

as a nameless term?

Here y is free variable.

We know what to do with x , but **we cannot see the binder** for y , so it is *not clear how “far away”* it might be and we do not know *what number* to assign to it.

To deal with these **terms containing free variables**, we need the idea of a **naming context**.



Name Context

Definition: Suppose x_0 through x_n are variable names from ν . The naming context

$\Gamma = x_n, x_{n-1}, \dots, x_1, x_0$ assigns to each x_i the *de Bruijn index* i .

Note that the *rightmost variable* in the sequence is given the index 0 ; this matches the way we count *λ binders* — **from right to left** — when converting a named term to nameless form.



Name Context

- We write $\text{dom}(\Gamma)$ for the set $\{x_n, \dots, x_1, x_0\}$ of variable names mentioned in Γ
- e.g., $\Gamma = x \mapsto 4; y \mapsto 3; z \mapsto 2; a \mapsto 1; b \mapsto 0$, under this Γ , we have
 - $x (y z)$?
4 (3 2)
 - $\lambda w. y w$
 $\lambda. 4 0$
 - $\lambda w. \lambda a. x$
 $\lambda. \lambda. 6$

Shifting and Substitution

How to define substitution $[k \mapsto s] t$?



Shifting

- Under the naming context $\Gamma : x \mapsto 1, z \mapsto 2$
 $[1 \mapsto 2 (\lambda. 0)] \lambda. 2 \rightarrow ?$
i.e., $[x \mapsto z (\lambda w. w)] \lambda y. x \rightarrow ?$
- When a substitution **goes under a λ -abstraction**, as in $[1 \mapsto s](\lambda. 2)$ (i.e., $[x \mapsto s](\lambda y. x)$, assuming that **1** is the index of **x** in the outer context), *the context* in which the substitution is taking place becomes *one variable longer than the original*.
 - We need to *increment the indices* of the *free variables* in **s** so that they keep referring to *the same names in the new context* as they did before.
 - e.g., $s = 2 (\lambda. 0)$, , i.e., $s = z (\lambda w. w)$, assuming **2** is the index of **z** in the outer context, we need to shift the **2** but not the **0**
- Shifting is just the **auxiliary operation**: *renumber the indices of the free variables* in a term.



Shifting

DEFINITION [SHIFTING]: The d -place shift of a term \mathbf{t} above cutoff c , written $\uparrow_c^d(\mathbf{t})$, is defined as follows:

$$\begin{aligned}\uparrow_c^d(k) &= \begin{cases} k & \text{if } k < c \\ k + d & \text{if } k \geq c \end{cases} \\ \uparrow_c^d(\lambda. \mathbf{t}_1) &= \lambda. \uparrow_{c+1}^d(\mathbf{t}_1) \\ \uparrow_c^d(\mathbf{t}_1 \mathbf{t}_2) &= \uparrow_c^d(\mathbf{t}_1) \uparrow_c^d(\mathbf{t}_2)\end{aligned}$$

We write $\uparrow^d(\mathbf{t})$ for $\uparrow_0^d(\mathbf{t})$.

□

1. What is $\uparrow^2(\lambda. \lambda. 1 (0 2))$?
2. What is $\uparrow^2(\lambda. 0 1 (\lambda. 0 1 2))$?



Substitution

DEFINITION [SUBSTITUTION]: The substitution of a term s for variable number j in a term t , written $[j \mapsto s]t$, is defined as follows:

$$\begin{aligned} [j \mapsto s]k &= \begin{cases} s & \text{if } k = j \\ k & \text{otherwise} \end{cases} \\ [j \mapsto s](\lambda.t_1) &= \lambda.[j+1 \mapsto \uparrow^1(s)]t_1 \\ [j \mapsto s](t_1 t_2) &= ([j \mapsto s]t_1 [j \mapsto s]t_2) \end{aligned}$$

□

$$\begin{aligned} [x \mapsto s]x &= s \\ [x \mapsto s]y &= y && \text{if } y \neq x \\ [x \mapsto s](\lambda y.t_1) &= \lambda y.[x \mapsto s]t_1 && \text{if } y \neq x \text{ and } y \notin FV(s) \\ [x \mapsto s](t_1 t_2) &= [x \mapsto s]t_1 [x \mapsto s]t_2 \end{aligned}$$



Evaluation

- To define the *evaluation relation* on nameless terms, the **only thing** we *need to change* (i.e., the only place where *variable names* are mentioned) is the *beta-reduction rule* (*computation rules*), while keep the other rules identical to what as Figure 5-3.

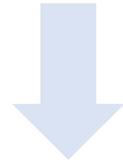
$$(\lambda x. t_{12}) t_2 \rightarrow [x \mapsto t_2]t_{12},$$

- How to change the above rule for nameless representation?

Evaluation

- Example:

$$(\lambda x. t_{12}) t_2 \rightarrow [x \mapsto t_2] t_{12},$$



$$(\lambda. t_{12}) v_2 \rightarrow \uparrow^{-1}([0 \mapsto \uparrow^1(v_2)] t_{12})$$

$$(\lambda. 1\ 0\ 2)\ (\lambda. 0) \rightarrow 0\ (\lambda. 0)\ 1$$



Homework

- Read Chapter 6.
 - Do Exercise 6.3.2.
- 6.3.2 EXERCISE [★★★]: De Bruijn’s original article actually contained two different proposals for nameless representations of terms: the deBruijn *indices* presented here, which number lambda-binders “from the inside out,” and *de Bruijn levels*, which number binders “from the outside in.” For example, the term $\lambda x. (\lambda y. x y) x$ is represented using deBruijn indices as $\lambda. (\lambda. 1 0) 0$ and using deBruijn levels as $\lambda. (\lambda. 0 1) 0$. Define this variant precisely and show that the representations of a term using indices and levels are isomorphic (i.e., each can be recovered uniquely from the other). \square
- Read Chapter 7 and digest the *fulluntyped* implementation includes extensions such as numbers and booleans.